

# Regular Languages and Finite State Automata

Data structures and algorithms  
for Computational Linguistics III

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# Why study finite-state automata?

- Unlike some of the abstract machines we discussed, finite-state automata are efficient models of computation
- There are many applications
  - Electronic circuit design
  - Workflow management
  - Games
  - Pattern matching
  - ...

But more importantly ;-)

- Tokenization, stemming
- Morphological analysis
- Shallow parsing/chunking
- ...

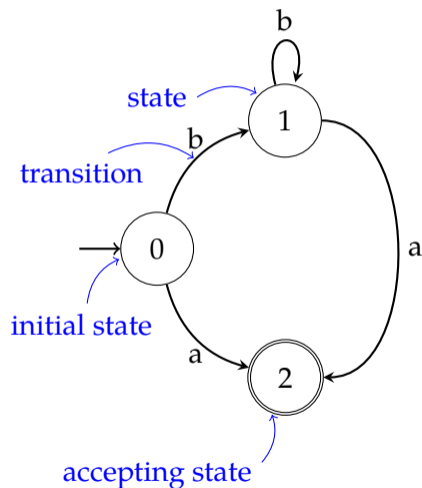
# Finite-state automata (FSA)

- A finite-state machine is in one of a finite-number of states in a given time
- The machine changes its state based on its input
- Every regular language is generated/recognized by an FSA
- Every FSA generates/recognizes a regular language
- Two flavors:
  - *Deterministic finite automata* (DFA)
  - *Non-deterministic finite automata* (NFA)

Note: the NFA is a superset of DFA.

# DFA as a graph

- States are represented as nodes
- Transitions are shown by the edges, labeled with symbols from an alphabet
- One of the states is marked as the *initial state*
- Some states are accepting states



## DFA: formal definition

Formally, a finite state automaton,  $M$ , is a tuple  $(\Sigma, Q, q_0, F, \Delta)$  with

$\Sigma$  is the alphabet, a finite set of symbols

$Q$  a finite set of states

$q_0$  is the start state,  $q_0 \in Q$

$F$  is the set of final states,  $F \subseteq Q$

$\Delta$  is a function that takes a state and a symbol in the alphabet, and returns another state ( $\Delta : Q \times \Sigma \rightarrow Q$ )

At any given time, for any input,  
a DFA has a single well-defined action to take.

# DFA: formal definition

## an example

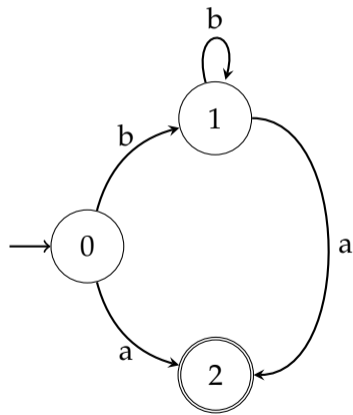
$$\Sigma = \{a, b\}$$

$$Q = \{q_0, q_1, q_2\}$$

$$q_0 = q_0$$

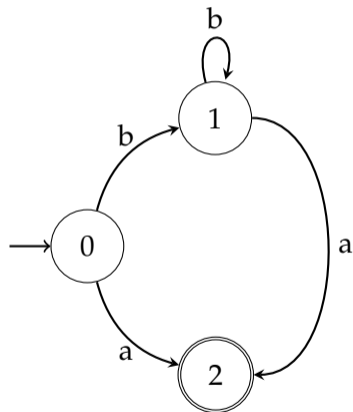
$$F = \{q_2\}$$

$$\Delta = \{(q_0, a) \rightarrow q_2, \quad (q_0, b) \rightarrow q_1, \\ (q_1, a) \rightarrow q_2, \quad (q_1, b) \rightarrow q_1\}$$



## Another note on DFA

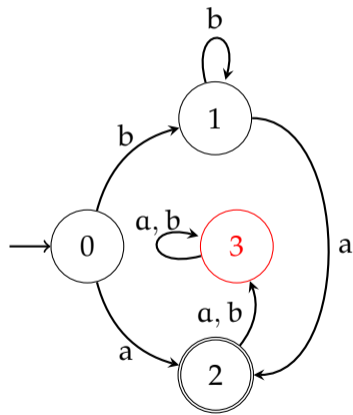
- Is this FSA deterministic?



## Another note on DFA

error or sink state

- Is this FSA deterministic?
- To make all transitions well-defined, we can add a sink (or error) state

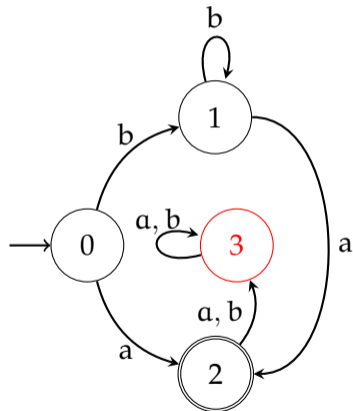




## Another note on DFA

### error or sink state

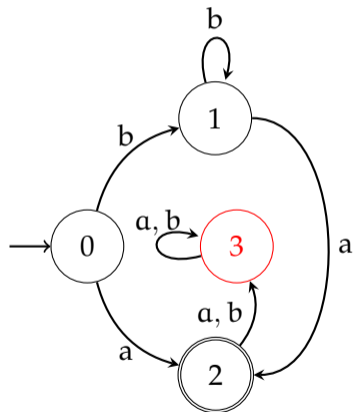
- Is this FSA deterministic?
- To make all transitions well-defined, we can add a sink (or error) state
- For brevity, we skip the explicit error state



## Another note on DFA

### error or sink state

- Is this FSA deterministic?
- To make all transitions well-defined, we can add a sink (or error) state
- For brevity, we skip the explicit error state
  - In that case, when we reach a dead end, recognition fails

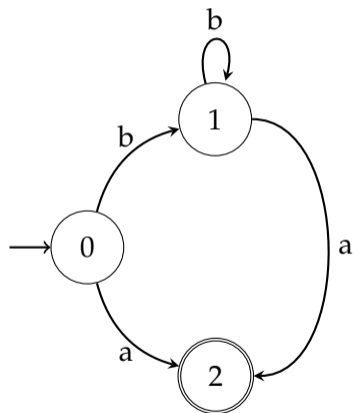


## DFA: the transition table

transition table			
		<i>symbol</i>	
		<b>a</b>	<b>b</b>
<i>state</i>	→ <b>0</b>	2	1
	<b>1</b>	2	1
	* <b>2</b>	∅	∅

→ marks the start state

\* marks the accepting state(s)

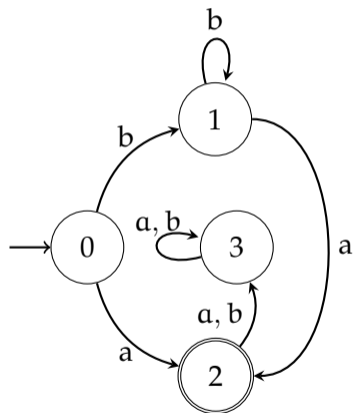


## DFA: the transition table

transition table			
		<i>symbol</i>	
		<b>a</b>	<b>b</b>
<i>state</i>	→ <b>0</b>	2	1
	<b>1</b>	2	1
	* <b>2</b>	3	3
	<b>3</b>	3	3

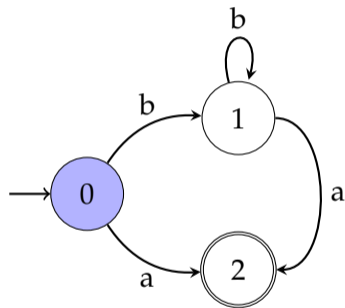
→ marks the start state

\* marks the accepting state(s)



# DFA recognition

1. Start at  $q_0$
2. Process an input symbol, move accordingly
3. Accept if in a final state at the end of the input

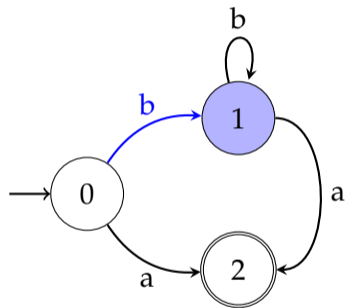


Input: 

b	b	a
---	---	---

# DFA recognition

1. Start at  $q_0$
2. Process an input symbol, move accordingly
3. Accept if in a final state at the end of the input

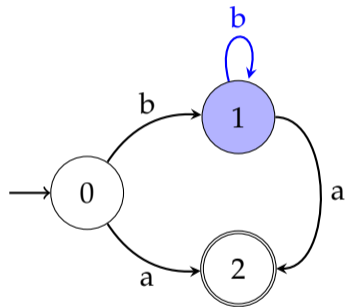


Input: 

b	b	a
---	---	---

# DFA recognition

1. Start at  $q_0$
2. Process an input symbol, move accordingly
3. Accept if in a final state at the end of the input

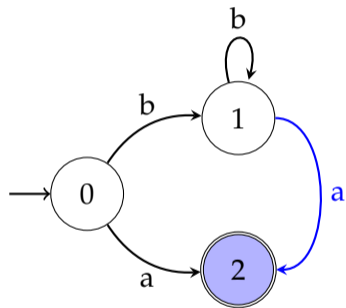


Input: 

b	b	a
---	---	---

# DFA recognition

1. Start at  $q_0$
2. Process an input symbol, move accordingly
3. Accept if in a final state at the end of the input



Input: 

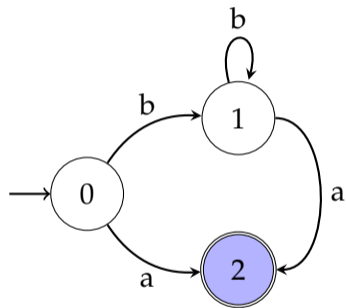
b	b	a
---	---	---

↓



# DFA recognition

1. Start at  $q_0$
2. Process an input symbol, move accordingly
3. Accept if in a final state at the end of the input



Input: 

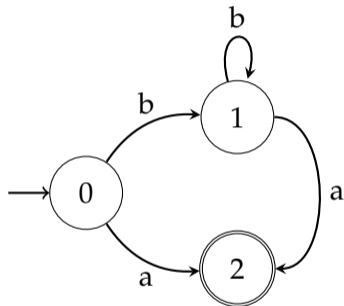
b	b	a
---	---	---

A blue arrow points to the final 'a' in the input sequence.

## DFA recognition

1. Start at  $q_0$
2. Process an input symbol, move accordingly
3. Accept if in a final state at the end of the input

- What is the complexity of the algorithm?
- How about inputs:
  - bbbb
  - aa

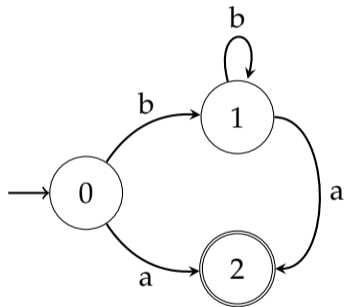


Input: 

b	b	a
---	---	---

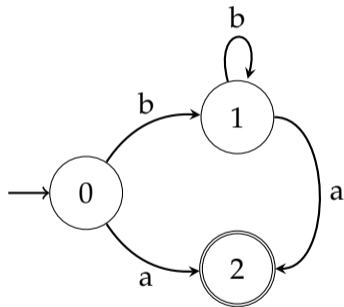
## A few questions

- What is the language recognized by this FSA?



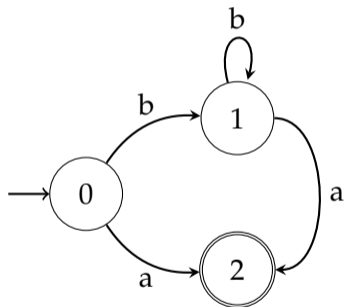
## A few questions

- What is the language recognized by this FSA?
- Can you draw a simpler DFA for the same language?



## A few questions

- What is the language recognized by this FSA?
- Can you draw a simpler DFA for the same language?
- Draw a DFA recognizing strings with even number of 'a's over  $\Sigma = \{a, b\}$



# Non-deterministic finite automata

## Formal definition

A non-deterministic finite state automaton,  $M$ , is a tuple  $(\Sigma, Q, q_0, F, \Delta)$  with

$\Sigma$  is the alphabet, a finite set of symbols

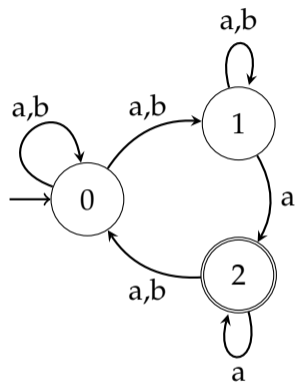
$Q$  a finite set of states

$q_0$  is the start state,  $q_0 \in Q$

$F$  is the set of final states,  $F \subseteq Q$

$\Delta$  is a function from  $(Q, \Sigma)$  to  $P(Q)$ , power set of  $Q$  ( $\Delta : Q \times \Sigma \rightarrow P(Q)$ )

## An example NFA



transition table

		<i>symbol</i>	
		<b>a</b>	<b>b</b>
<i>state</i>	→ <b>0</b>	0,1	0,1
	<b>1</b>	1,2	1
	<b>*2</b>	0,2	0

- We have nondeterminism, e.g., if the first input is a, we need to choose between states 0 or 1
- Transition table cells have *sets* of states

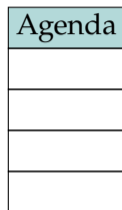
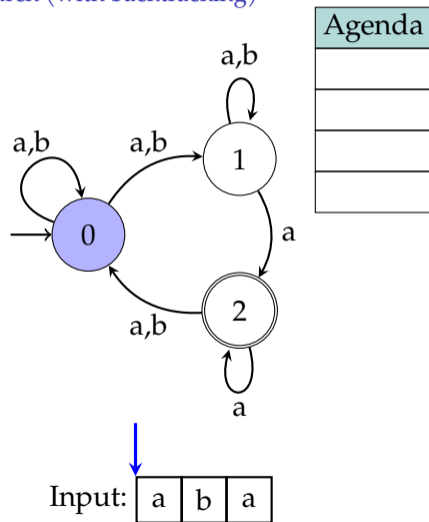
# Dealing with non-determinism

- Follow one of the links, store alternatives, and *backtrack* on failure
- Follow all options in parallel
- Use dynamic programming (e.g., as in chart parsing)



# NFA recognition

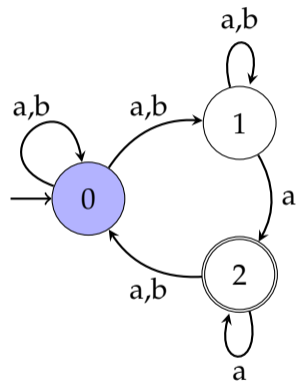
as search (with backtracking)



1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. Get the next action from the agenda, act
4. At the end of input
  - Accept if in an accepting state
  - Reject not in accepting state & agenda empty
  - Backtrack otherwise

# NFA recognition

as search (with backtracking)



Agenda
$(q_0, 1)$
$(q_1, 1)$

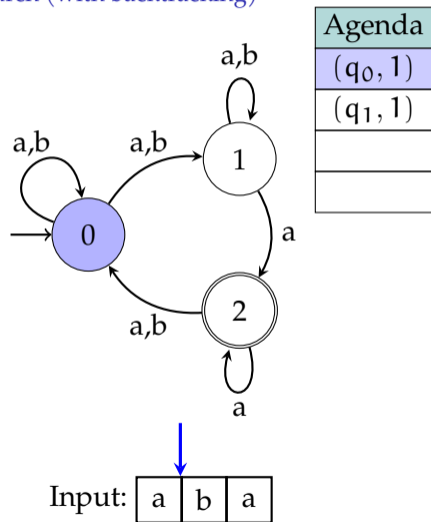
Input: 

a	b	a
---	---	---

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. Get the next action from the agenda, act
4. At the end of input
  - Accept if in an accepting state
  - Reject not in accepting state & agenda empty
  - Backtrack otherwise

# NFA recognition

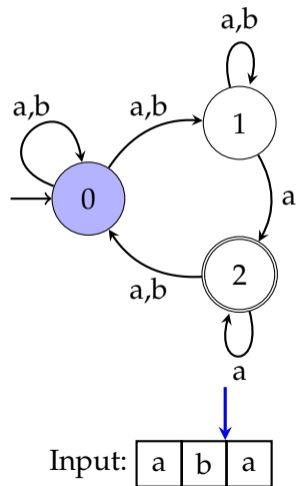
as search (with backtracking)



1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. **Get the next action from the agenda, act**
4. At the end of input  
 Accept if in an accepting state  
 Reject not in accepting state & agenda empty  
 Backtrack otherwise

# NFA recognition

as search (with backtracking)

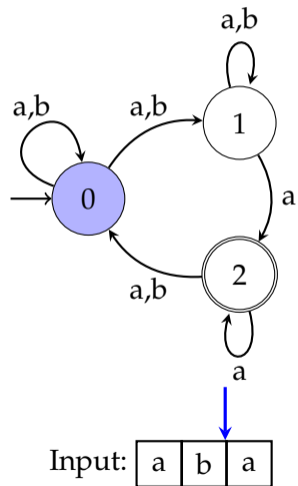


Agenda
$(q_0, 2)$
$(q_1, 2)$
$(q_1, 1)$

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. Get the next action from the agenda, act
4. At the end of input
  - Accept if in an accepting state
  - Reject not in accepting state & agenda empty
  - Backtrack otherwise

# NFA recognition

as search (with backtracking)

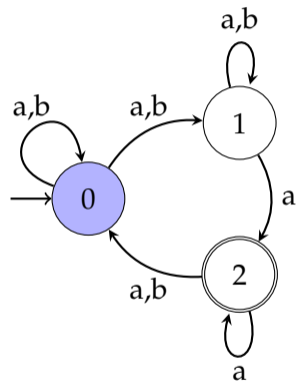


Agenda
$(q_0, 2)$
$(q_1, 2)$
$(q_1, 1)$

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. **Get the next action from the agenda, act**
4. At the end of input  
 Accept if in an accepting state  
 Reject not in accepting state & agenda empty  
 Backtrack otherwise

# NFA recognition

as search (with backtracking)



Agenda
$(q_0, 3)$
$(q_1, 3)$
$(q_1, 2)$
$(q_1, 1)$

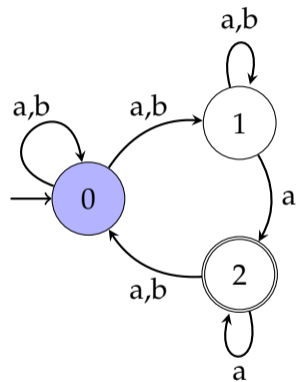
Input: 

a	b	a
---	---	---

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. Get the next action from the agenda, act
4. At the end of input
  - Accept if in an accepting state
  - Reject not in accepting state & agenda empty
  - Backtrack otherwise

# NFA recognition

as search (with backtracking)



Agenda
(q <sub>0</sub> , 3)
(q <sub>1</sub> , 3)
(q <sub>1</sub> , 2)
(q <sub>1</sub> , 1)

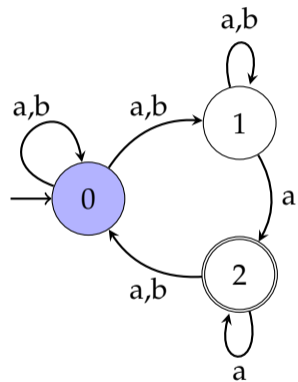
Input: 

a	b	a
---	---	---

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. **Get the next action from the agenda, act**
4. At the end of input
  - Accept if in an accepting state
  - Reject not in accepting state & agenda empty
  - Backtrack otherwise

# NFA recognition

as search (with backtracking)



Agenda
(q <sub>1</sub> , 3)
(q <sub>1</sub> , 2)
(q <sub>1</sub> , 1)

Input: 

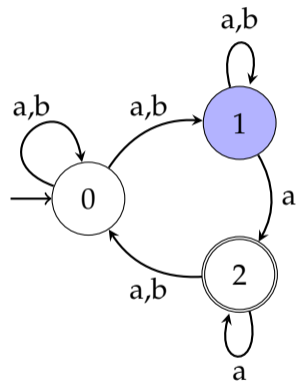
a	b	a
---	---	---

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. Get the next action from the agenda, act
4. At the end of input
  - Accept if in an accepting state
  - Reject not in accepting state & agenda empty
  - Backtrack otherwise



# NFA recognition

as search (with backtracking)



Agenda
(q <sub>1</sub> , 3)
(q <sub>1</sub> , 2)
(q <sub>1</sub> , 1)

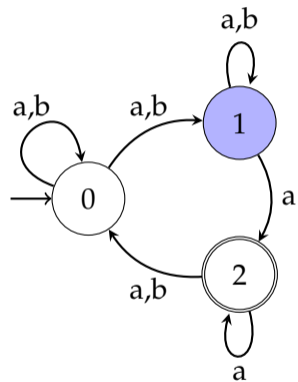
Input: 

a	b	a
---	---	---

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. **Get the next action from the agenda, act**
4. At the end of input  
 Accept if in an accepting state  
 Reject not in accepting state & agenda empty  
 Backtrack otherwise

# NFA recognition

as search (with backtracking)



Agenda
(q <sub>1</sub> , 2)
(q <sub>1</sub> , 1)

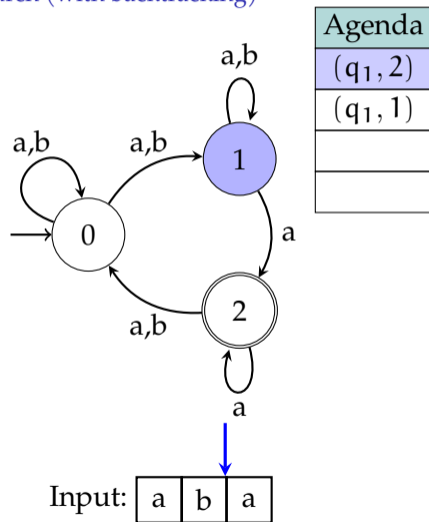
Input: 

a	b	a
---	---	---

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. Get the next action from the agenda, act
4. At the end of input  
 Accept if in an accepting state  
 Reject not in accepting state & agenda empty  
 Backtrack otherwise

# NFA recognition

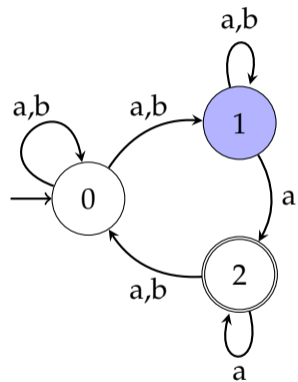
as search (with backtracking)



1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. **Get the next action from the agenda, act**
4. At the end of input  
 Accept if in an accepting state  
 Reject not in accepting state & agenda empty  
 Backtrack otherwise

# NFA recognition

as search (with backtracking)



Agenda
(q <sub>2</sub> , 3)
(q <sub>1</sub> , 3)
(q <sub>1</sub> , 1)

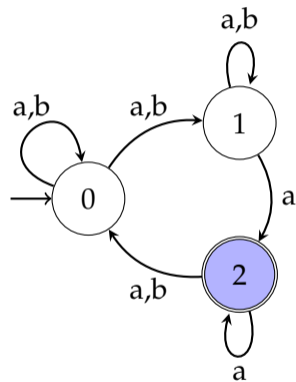
Input: 

a	b	a
---	---	---

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. Get the next action from the agenda, act
4. At the end of input  
 Accept if in an accepting state  
 Reject not in accepting state & agenda empty  
 Backtrack otherwise

# NFA recognition

as search (with backtracking)



Agenda
(q <sub>2</sub> , 3)
(q <sub>1</sub> , 3)
(q <sub>1</sub> , 1)

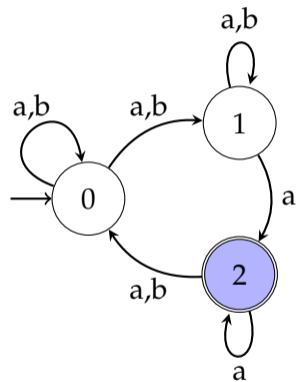
Input: 

a	b	a
---	---	---

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. **Get the next action from the agenda, act**
4. At the end of input  
 Accept if in an accepting state  
 Reject not in accepting state & agenda empty  
 Backtrack otherwise

# NFA recognition

as search (with backtracking)



Agenda
(q <sub>1</sub> , 3)
(q <sub>1</sub> , 1)

Input: 

a	b	a
---	---	---

1. Start at  $q_0$
2. Take the next input, place all possible actions to an *agenda*
3. Get the next action from the agenda, act
4. At the end of input  
 Accept if in an accepting state  
 Reject not in accepting state & agenda empty  
 Backtrack otherwise

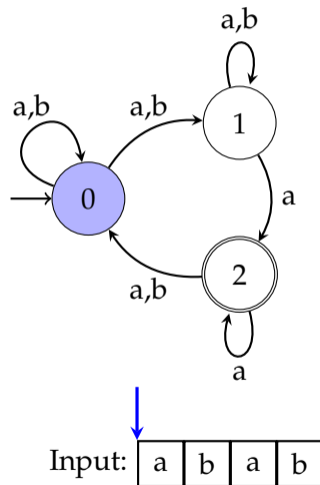
# NFA recognition as search

## summary

- Worst time complexity is exponential
  - Complexity is worse if we want to enumerate all derivations
- We used a stack as *agenda*, performing a depth-first search
- A queue would result in breadth-first search
- If we have a reasonable heuristic A\* search may be an option
- Machine learning methods may also guide finding a fast or the best solution

# NFA recognition

parallel version

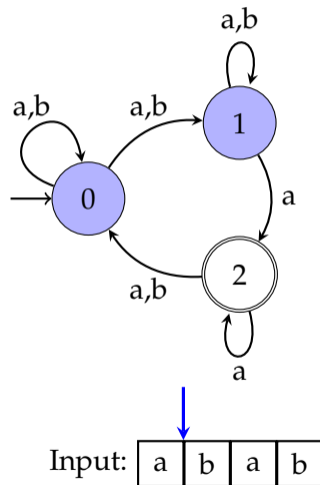


1. Start at  $q_0$
2. Take the next input, mark all possible next states
3. If an accepting state is marked at the end of the input, accept



# NFA recognition

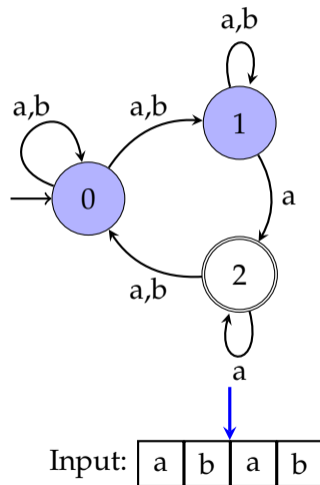
parallel version



1. Start at  $q_0$
2. Take the next input, mark all possible next states
3. If an accepting state is marked at the end of the input, accept

# NFA recognition

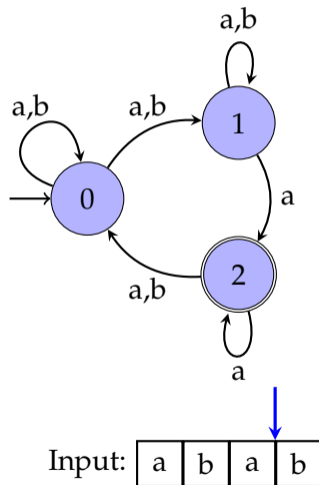
parallel version



1. Start at  $q_0$
2. Take the next input, mark all possible next states
3. If an accepting state is marked at the end of the input, accept

# NFA recognition

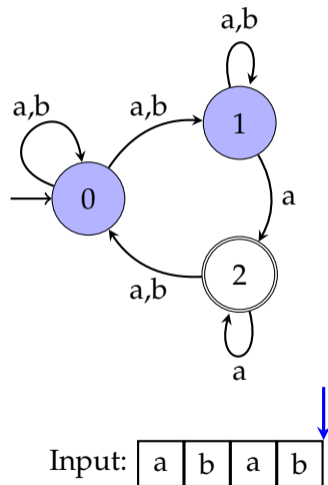
parallel version



1. Start at  $q_0$
2. Take the next input, mark all possible next states
3. If an accepting state is marked at the end of the input, accept

# NFA recognition

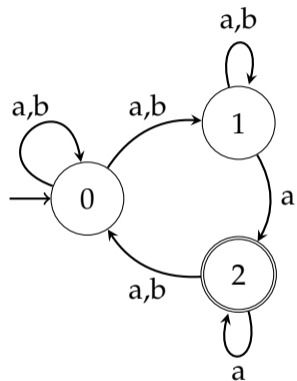
parallel version



1. Start at  $q_0$
2. Take the next input, mark all possible next states
3. If an accepting state is marked at the end of the input, accept

# NFA recognition

parallel version



Input: 

a	b	a	b
---	---	---	---

1. Start at  $q_0$
2. Take the next input, mark all possible next states
3. If an accepting state is marked at the end of the input, accept

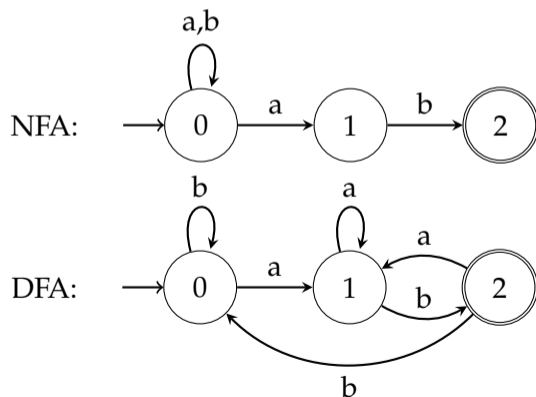
Note: the process is *deterministic*, and *finite-state*.

## An exercise

Construct an NFA and a DFA for the language over  $\Sigma = \{a, b\}$  where all sentences end with  $ab$ .

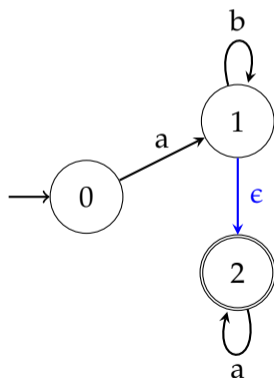
## An exercise

Construct an NFA and a DFA for the language over  $\Sigma = \{a, b\}$  where all sentences end with  $ab$ .



## One more complication: $\epsilon$ transitions

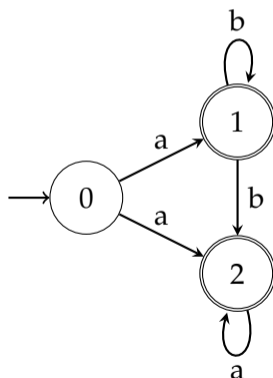
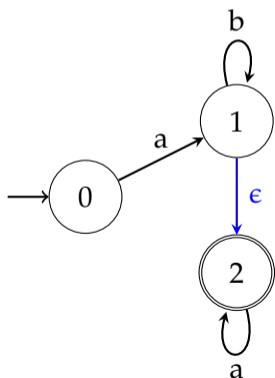
- An extension of NFA,  $\epsilon$ -NFA, allows moving without consuming an input symbol, indicated by an  $\epsilon$ -transition (sometimes called a  $\lambda$ -transition)
- Any  $\epsilon$ -NFA can be converted to an NFA



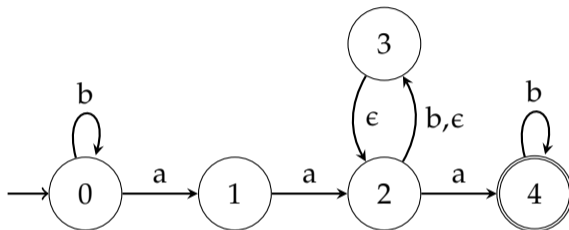


## One more complication: $\epsilon$ transitions

- An extension of NFA,  $\epsilon$ -NFA, allows moving without consuming an input symbol, indicated by an  $\epsilon$ -transition (sometimes called a  $\lambda$ -transition)
- Any  $\epsilon$ -NFA can be converted to an NFA



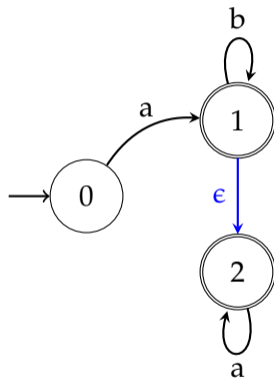
## $\epsilon$ -transitions need attention



- How does the (depth-first) **NFA recognition algorithm** we described earlier work on this automaton?
- Can we do without  $\epsilon$  transitions?

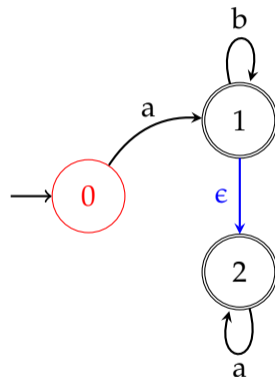
# $\epsilon$ removal

- We start with finding the  $\epsilon$ -closure of all states



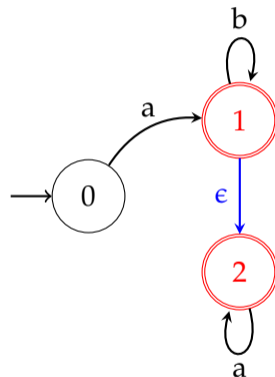
# $\epsilon$ removal

- We start with finding the  $\epsilon$ -closure of all states
  - $\epsilon$ -closure( $q_0$ ) =  $\{q_0\}$



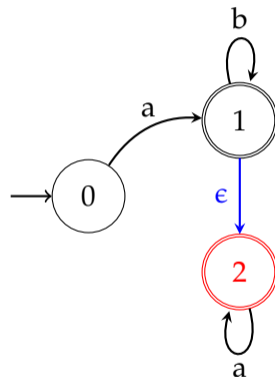
# $\epsilon$ removal

- We start with finding the  $\epsilon$ -closure of all states
  - $\epsilon$ -closure( $q_0$ ) =  $\{q_0\}$
  - $\epsilon$ -closure( $q_1$ ) =  $\{q_1, q_2\}$



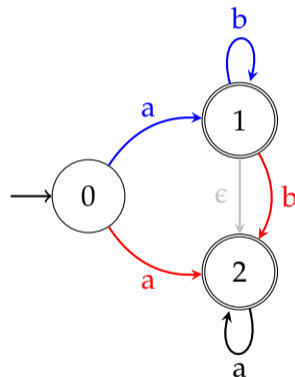
# $\epsilon$ removal

- We start with finding the  $\epsilon$ -closure of all states
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  - $\epsilon$ -closure( $q_2$ ) =  $\{q_2\}$



# $\epsilon$ removal

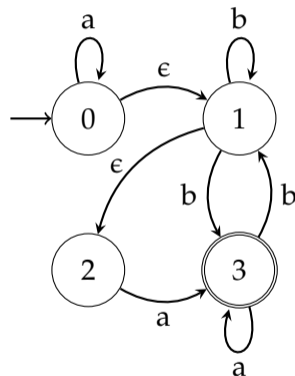
- We start with finding the  $\epsilon$ -closure of all states
  - $\epsilon$ -closure( $q_0$ ) =  $\{q_0\}$
  - $\epsilon$ -closure( $q_1$ ) =  $\{q_1, q_2\}$
  - $\epsilon$ -closure( $q_2$ ) =  $\{q_2\}$
- Replace each arc to each state with arc(s) to all states in the  $\epsilon$ -closure of the state



# $\epsilon$ removal

a(nother) solution with the transition table

transition table

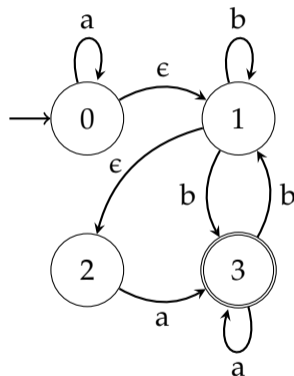




# $\epsilon$ removal

a(nother) solution with the transition table

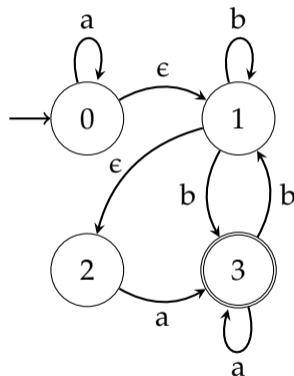
transition table				
		<i>symbol</i>		
		<b>a</b>	<b>b</b>	<b><math>\epsilon</math></b>
<i>state</i>	$\rightarrow$ <b>0</b>	0	$\emptyset$	1
	<b>1</b>	$\emptyset$	1,3	2
	<b>2</b>	3	$\emptyset$	$\emptyset$
	<b>*3</b>	3	1	$\emptyset$



# $\epsilon$ removal

a(nother) solution with the transition table

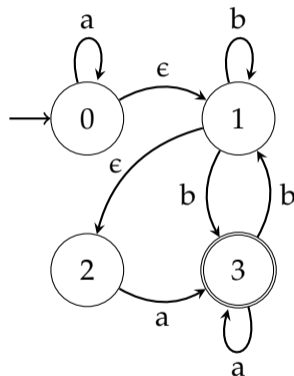
transition table					
		<i>symbol</i>			
		<b>a</b>	<b>b</b>	<b><math>\epsilon</math></b>	<b><math>\epsilon^*</math></b>
<i>state</i>	<b>→0</b>	0	$\emptyset$	1	0,1,2
	<b>1</b>	$\emptyset$	1,3	2	
	<b>2</b>	3	$\emptyset$	$\emptyset$	
	<b>*3</b>	3	1	$\emptyset$	



# $\epsilon$ removal

a(nother) solution with the transition table

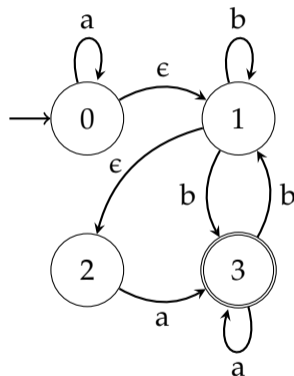
transition table					
		<i>symbol</i>			
		<b>a</b>	<b>b</b>	<b><math>\epsilon</math></b>	<b><math>\epsilon^*</math></b>
<i>state</i>	$\rightarrow$ 0	0	$\emptyset$	1	0,1,2
	1	$\emptyset$	1,3	2	1,2
	2	3	$\emptyset$	$\emptyset$	2
	*3	3	1	$\emptyset$	



# $\epsilon$ removal

a(nother) solution with the transition table

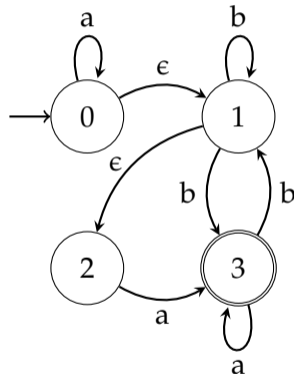
transition table					
		<i>symbol</i>			
		<b>a</b>	<b>b</b>	<b><math>\epsilon</math></b>	<b><math>\epsilon^*</math></b>
<i>state</i>	<b>→0</b>	0	$\emptyset$	1	0,1,2
	<b>1</b>	$\emptyset$	1,3	2	1,2
	<b>2</b>	3	$\emptyset$	$\emptyset$	2
	<b>*3</b>	3	1	$\emptyset$	3



# $\epsilon$ removal

a(nother) solution with the transition table

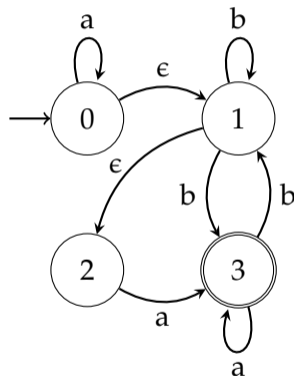
transition table							
		<i>symbol</i>					
		<b>a</b>	<b>b</b>	$\epsilon$	$\epsilon^*$		
<i>state</i>	$\rightarrow$ <b>0</b>	0	$\emptyset$	1	0,1,2	$\Rightarrow$	$\rightarrow$ <b>0</b>
	<b>1</b>	$\emptyset$	1,3	2	1,2		<b>1</b>
	<b>2</b>	3	$\emptyset$	$\emptyset$	2		<b>2</b>
	<b>*3</b>	3	1	$\emptyset$	3		<b>*3</b>



# $\epsilon$ removal

a(nother) solution with the transition table

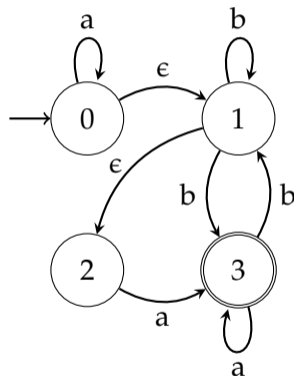
transition table									
		<i>symbol</i>						<i>symbol</i>	
		<b>a</b>	<b>b</b>	$\epsilon$	$\epsilon^*$			<b>a</b>	<b>b</b>
<i>state</i>	$\rightarrow$ <b>0</b>	<b>0</b>	$\emptyset$	1	0,1,2	$\Rightarrow$	$\rightarrow$ <b>0</b>	0,3	
	<b>1</b>	$\emptyset$	1,3	2	1,2		<b>1</b>		
	<b>2</b>	<b>3</b>	$\emptyset$	$\emptyset$	2		<b>2</b>		
	<b>*3</b>	3	1	$\emptyset$	3		<b>*3</b>		



# $\epsilon$ removal

a(nother) solution with the transition table

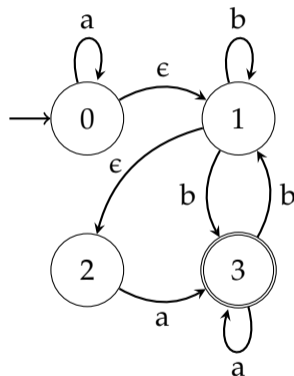
transition table									
		<i>symbol</i>						<i>symbol</i>	
		<b>a</b>	<b>b</b>	$\epsilon$	$\epsilon^*$			<b>a</b>	<b>b</b>
<i>state</i>	$\rightarrow$ <b>0</b>	0	$\emptyset$	1	0,1,2	$\Rightarrow$	$\rightarrow$ <b>0</b>	0,3	1,3
	<b>1</b>	$\emptyset$	1,3	2	1,2		<b>1</b>		
	<b>2</b>	3	$\emptyset$	$\emptyset$	2		<b>2</b>		
	<b>*3</b>	3	1	$\emptyset$	3		<b>*3</b>		



# $\epsilon$ removal

a(nother) solution with the transition table

transition table									
		<i>symbol</i>						<i>symbol</i>	
		<b>a</b>	<b>b</b>	$\epsilon$	$\epsilon^*$			<b>a</b>	<b>b</b>
<i>state</i>	$\rightarrow$ <b>0</b>	0	$\emptyset$	1	0,1,2	$\Rightarrow$	$\rightarrow$ <b>0</b>	0,3	1,3
	<b>1</b>	$\emptyset$	1,3	2	1,2		<b>1</b>	3	
	<b>2</b>	<b>3</b>	$\emptyset$	$\emptyset$	2		<b>2</b>		
	<b>*3</b>	3	1	$\emptyset$	3		<b>*3</b>		

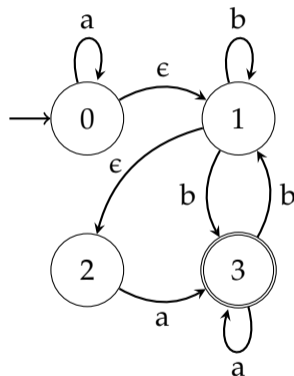




# $\epsilon$ removal

a(nother) solution with the transition table

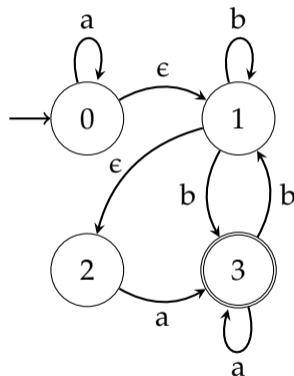
transition table									
		<i>symbol</i>						<i>symbol</i>	
		<b>a</b>	<b>b</b>	$\epsilon$	$\epsilon^*$			<b>a</b>	<b>b</b>
<i>state</i>	$\rightarrow$ <b>0</b>	0	$\emptyset$	1	0,1,2	$\Rightarrow$	$\rightarrow$ <b>0</b>	0,3	1,3
	<b>1</b>	$\emptyset$	1,3	2	1,2		<b>1</b>	3	1,3
	<b>2</b>	3	$\emptyset$	$\emptyset$	2		<b>2</b>		
	<b>*3</b>	3	1	$\emptyset$	3		<b>*3</b>		



# $\epsilon$ removal

a(nother) solution with the transition table

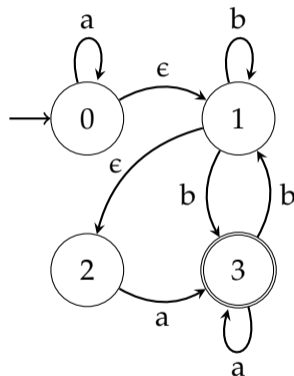
transition table									
		<i>symbol</i>						<i>symbol</i>	
		<b>a</b>	<b>b</b>	$\epsilon$	$\epsilon^*$			<b>a</b>	<b>b</b>
<i>state</i>	$\rightarrow$ <b>0</b>	0	$\emptyset$	1	0,1,2	$\Rightarrow$	$\rightarrow$ <b>0</b>	0,3	1,3
	<b>1</b>	$\emptyset$	1,3	2	1,2		<b>1</b>	3	1,3
	<b>2</b>	<b>3</b>	$\emptyset$	$\emptyset$	2		<b>2</b>	3	
	<b>*3</b>	3	1	$\emptyset$	3		<b>*3</b>		



# $\epsilon$ removal

a(nother) solution with the transition table

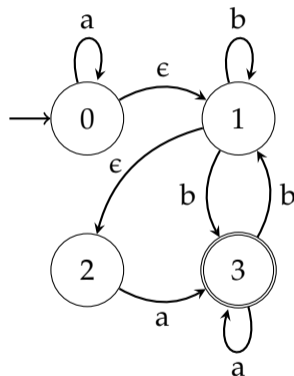
transition table									
		<i>symbol</i>						<i>symbol</i>	
		<b>a</b>	<b>b</b>	<b><math>\epsilon</math></b>	<b><math>\epsilon^*</math></b>			<b>a</b>	<b>b</b>
<i>state</i>	$\rightarrow$ <b>0</b>	0	$\emptyset$	1	0,1,2	$\Rightarrow$	$\rightarrow$ <b>0</b>	0,3	1,3
	<b>1</b>	$\emptyset$	1,3	2	1,2		<b>1</b>	3	1,3
	<b>2</b>	3	<del><math>\emptyset</math></del>	$\emptyset$	2		<b>2</b>	3	$\emptyset$
	<b>*3</b>	3	1	$\emptyset$	3		<b>*3</b>		



# $\epsilon$ removal

a(nother) solution with the transition table

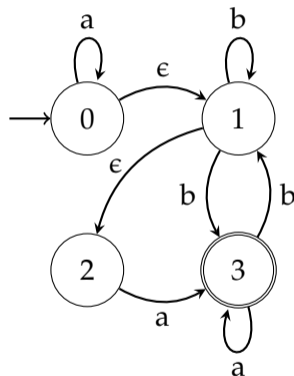
transition table									
		<i>symbol</i>						<i>symbol</i>	
		<b>a</b>	<b>b</b>	$\epsilon$	$\epsilon^*$			<b>a</b>	<b>b</b>
<i>state</i>	$\rightarrow$ <b>0</b>	0	$\emptyset$	1	0,1,2	$\Rightarrow$	$\rightarrow$ <b>0</b>	0,3	1,3
	<b>1</b>	$\emptyset$	1,3	2	1,2		<b>1</b>	3	1,3
	<b>2</b>	3	$\emptyset$	$\emptyset$	2		<b>2</b>	3	$\emptyset$
	<b>*3</b>	<b>3</b>	1	$\emptyset$	3		<b>*3</b>	3	



# $\epsilon$ removal

a(nother) solution with the transition table

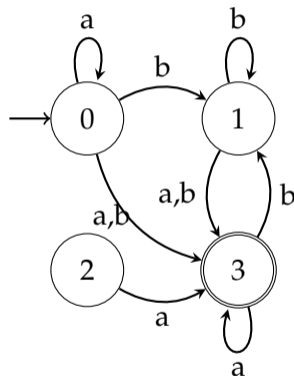
transition table									
		<i>symbol</i>						<i>symbol</i>	
		<b>a</b>	<b>b</b>	$\epsilon$	$\epsilon^*$			<b>a</b>	<b>b</b>
<i>state</i>	$\rightarrow$ <b>0</b>	0	$\emptyset$	1	0,1,2	$\Rightarrow$	$\rightarrow$ <b>0</b>	0,3	1,3
	<b>1</b>	$\emptyset$	1,3	2	1,2		<b>1</b>	3	1,3
	<b>2</b>	3	$\emptyset$	$\emptyset$	2		<b>2</b>	3	$\emptyset$
	<b>*3</b>	3	<b>1</b>	$\emptyset$	3		<b>*3</b>	3	1



# $\epsilon$ removal

a(nother) solution with the transition table

transition table									
		<i>symbol</i>						<i>symbol</i>	
		<b>a</b>	<b>b</b>	<b><math>\epsilon</math></b>	<b><math>\epsilon^*</math></b>			<b>a</b>	<b>b</b>
<i>state</i>	<b>→0</b>	0	$\emptyset$	1	0,1,2	<b>⇒</b>	<b>→0</b>	0,3	1,3
	<b>1</b>	$\emptyset$	1,3	2	1,2		<b>1</b>	3	1,3
	<b>2</b>	3	$\emptyset$	$\emptyset$	2		<b>2</b>	3	$\emptyset$
	<b>*3</b>	3	1	$\emptyset$	3		<b>*3</b>	3	1



# NFA–DFA equivalence

- The language recognized by every NFA is recognized by some DFA
- The set of DFA is a subset of the set of NFA (a DFA is also an NFA)
- The same is true for  $\epsilon$ -NFA
- All recognize/generate regular languages
- NFA can automatically be converted to the equivalent DFA

## Why do we use an NFA then?

- NFA (or  $\epsilon$ -NFA) are often easier to construct
  - Intuitive for humans (cf. earlier exercise)
  - Some representations are easy to convert to NFA rather than DFA, e.g., regular expressions
- NFA may require less memory (fewer states)



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### A quick exercise

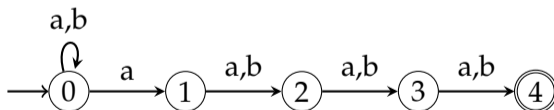
1. Construct (draw) an NFA for the language over  $\Sigma = \{a, b\}$ , such that 4th symbol from the end is an  $a$

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1. Construct (draw) an NFA for the language over  $\Sigma = \{a, b\}$ , such that 4th symbol from the end is an  $a$

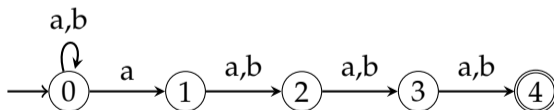


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A quick exercise – and a not-so-quick one

1. Construct (draw) an NFA for the language over  $\Sigma = \{a, b\}$ , such that 4th symbol from the end is an  $a$



2. Construct a DFA for the same language

# Determinization

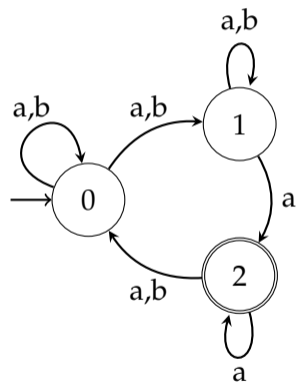
## the subset construction

Intuition: remember **the parallel NFA recognition**. We can consider an NFA being a deterministic machine which is at a **set of states** at any given time.

- *Subset construction* (sometimes called power set construction) uses this intuition to convert an NFA to a DFA
- The algorithm can be modified to handle  $\epsilon$ -transitions (or we can eliminate  $\epsilon$ 's as a preprocessing step)

# The subset construction

by example

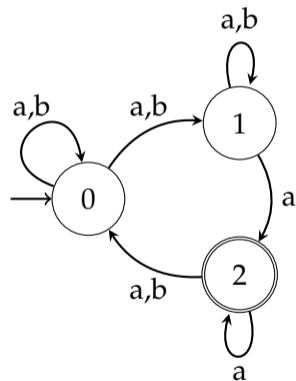


transition table with subsets

	<i>symbol</i>	
	<b>a</b>	<b>b</b>
$\emptyset$	$\emptyset$	$\emptyset$
$\rightarrow \{0\}$	$\{0, 1\}$	$\{0, 1\}$
$\{1\}$	$\{1, 2\}$	$\{1\}$
$* \{2\}$	$\{0, 2\}$	$\{0\}$
$\{0, 1\}$	$\{0, 1, 2\}$	$\{0, 1\}$
$* \{0, 2\}$	$\{0, 1, 2\}$	$\{0, 1\}$
$* \{1, 2\}$	$\{0, 1, 2\}$	$\{0, 1\}$
$* \{0, 1, 2\}$	$\{0, 1, 2\}$	$\{0, 1\}$

# The subset construction

by example



transition table with subsets

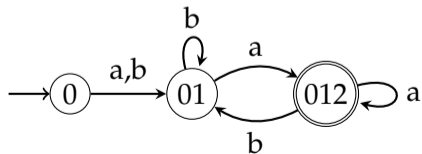
	<i>symbol</i>	
	<b>a</b>	<b>b</b>
<del><math>\emptyset</math></del>	<del><math>\emptyset</math></del>	<del><math>\emptyset</math></del>
$\rightarrow \{0\}$	$\{0, 1\}$	$\{0, 1\}$
<del><math>\{1\}</math></del>	<del><math>\{1, 2\}</math></del>	<del><math>\{1\}</math></del>
<del><math>\ast \{2\}</math></del>	<del><math>\{0, 2\}</math></del>	<del><math>\{0\}</math></del>
$\{0, 1\}$	$\{0, 1, 2\}$	$\{0, 1\}$
<del><math>\ast \{0, 2\}</math></del>	<del><math>\{0, 1, 2\}</math></del>	<del><math>\{0, 1\}</math></del>
<del><math>\ast \{1, 2\}</math></del>	<del><math>\{0, 1, 2\}</math></del>	<del><math>\{0, 1\}</math></del>
$\ast \{0, 1, 2\}$	$\{0, 1, 2\}$	$\{0, 1\}$

# The subset construction

by example: the resulting DFA

transition table without useless/inaccessible states

	<i>symbol</i>	
	<b>a</b>	<b>b</b>
$\rightarrow \{0\}$	$\{0, 1\}$	$\{0, 1\}$
$\{0, 1\}$	$\{0, 1, 2\}$	$\{0, 1\}$
$* \{0, 1, 2\}$	$\{0, 1, 2\}$	$\{0, 1\}$

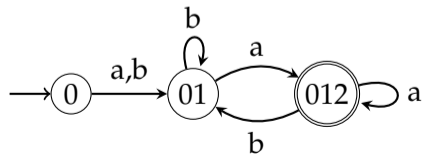


# The subset construction

by example: the resulting DFA

transition table without useless/inaccessible states

	<i>symbol</i>	
	<b>a</b>	<b>b</b>
$\rightarrow \{0\}$	$\{0, 1\}$	$\{0, 1\}$
$\{0, 1\}$	$\{0, 1, 2\}$	$\{0, 1\}$
$* \{0, 1, 2\}$	$\{0, 1, 2\}$	$\{0, 1\}$

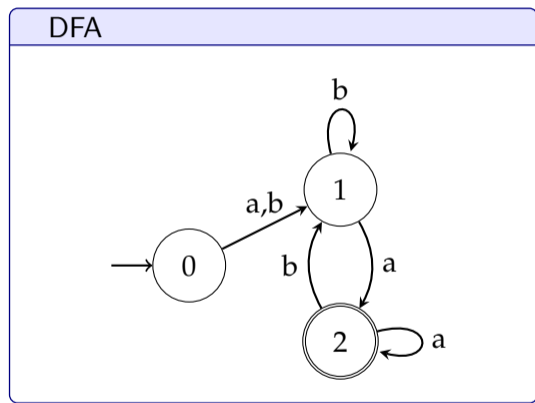
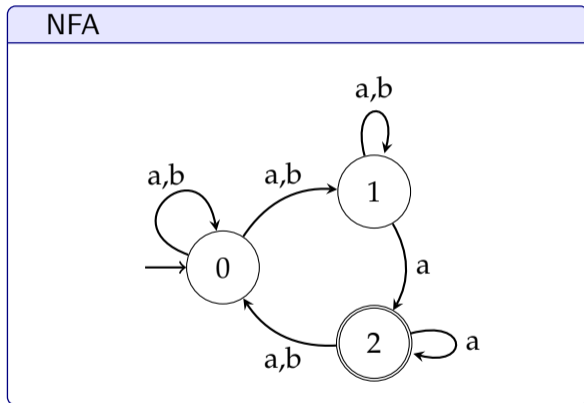


Do you remember the set of states marked during [parallel NFA recognition](#)?



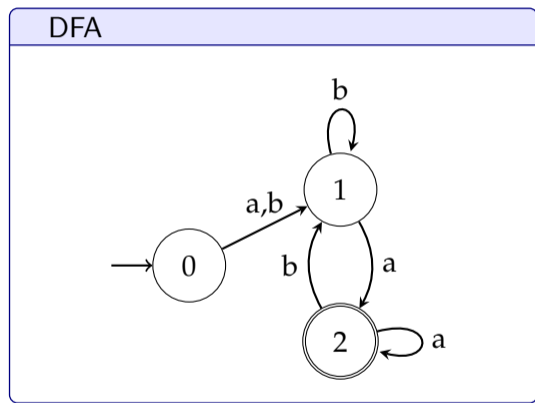
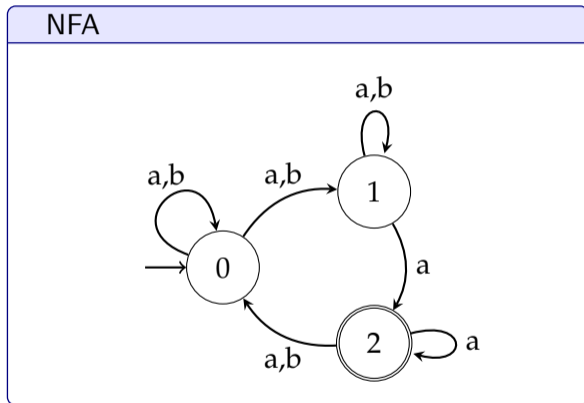
# The subset construction

by example: side by side



# The subset construction

by example: side by side

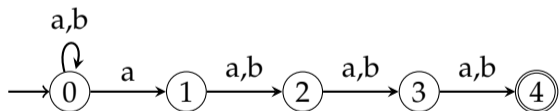


- What language do they recognize?

# The subset construction

## wrapping up

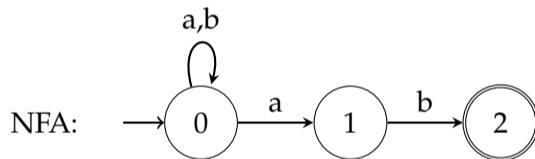
- In worst case, resulting DFA has  $2^n$  nodes
- Worst case is rather rare, number of nodes in an NFA and the converted DFA are often similar
- In practice, we do not need to enumerate all  $2^n$  subsets
- We've already seen a typical problematic case:



- We can also skip the unreachable states during subset construction

## Yet another exercise

Determinize the following automaton



## Regular languages: definition

A regular grammar is a tuple  $G = (\Sigma, N, S, R)$  where

$\Sigma$  is an alphabet of terminal symbols

$N$  are a set of non-terminal symbols

$S$  is a special 'start' symbol  $\in N$

$R$  is a set of rewrite rules following one of the following patterns ( $A, B \in N$ ,  $a \in \Sigma$ ,  $\epsilon$  is the empty string)

### Left regular

1.  $A \rightarrow a$
2.  $A \rightarrow Ba$
3.  $A \rightarrow \epsilon$

### Right regular

1.  $A \rightarrow a$
2.  $A \rightarrow aB$
3.  $A \rightarrow \epsilon$

## Regular languages: another definition

A language is regular if there is an FSA that recognizes it

- We denote the language recognized by a finite state automaton  $M$ , as  $\mathcal{L}(M)$
- The above definition reformulated: if a language  $L$  is regular, there is a DFA  $M$ , such that  $\mathcal{L}(M) = L$
- Remember: any NFA (with or without  $\epsilon$  transitions) can be converted to a DFA

## Some operations on regular languages (and FSA)

$L_1 L_2$  Concatenation of two languages  $L_1$  and  $L_2$ : any sentence of  $L_1$  followed by any sentence of  $L_2$

$L^*$  Kleene star of  $L$ :  $L$  concatenated by itself 0 or more times

$L^R$  Reverse of  $L$ : reverse of any string in  $L$

$\bar{L}$  Complement of  $L$ : all strings in  $\Sigma_L^*$  except the ones in  $L$  ( $\Sigma_L^* - L$ )

$L_1 \cup L_2$  Union of languages  $L_1$  and  $L_2$ : strings that are in any of the languages

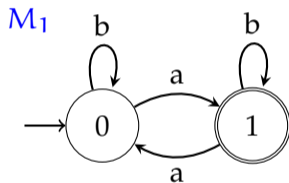
$L_1 \cap L_2$  Intersection of languages  $L_1$  and  $L_2$ : strings that are in both languages

Regular languages are closed under all of these operations.

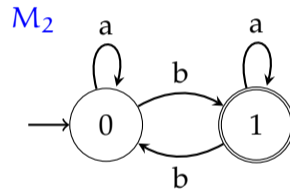
# Two example FSA

what languages do they accept?

$L_1 = \mathcal{L}(M_1)$



$L_2 = \mathcal{L}(M_2)$

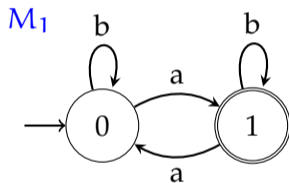




## Two example FSA

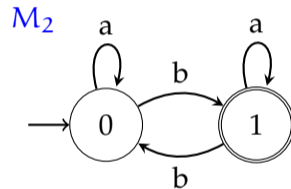
what languages do they accept?

$L_1 = \mathcal{L}(M_1)$



Odd number of  $a$ 's over  $\{a, b\}$ .

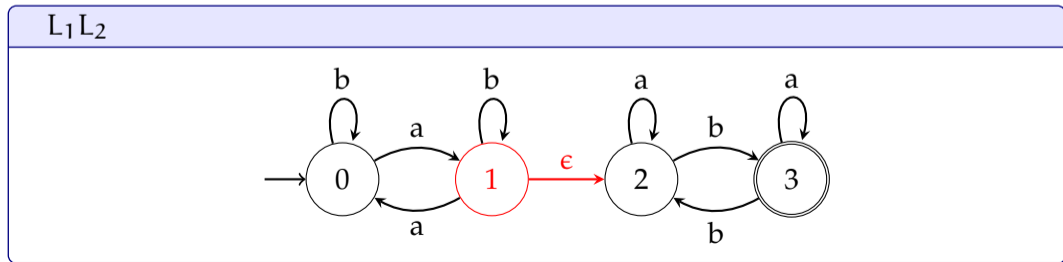
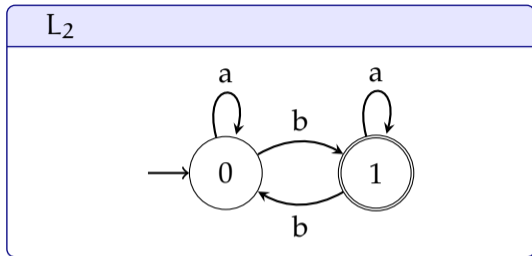
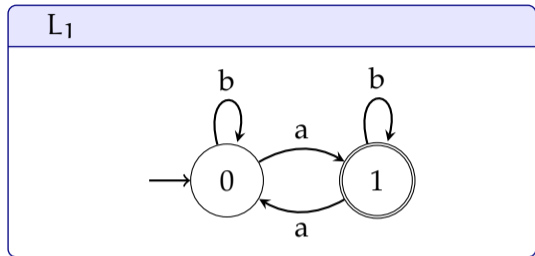
$L_2 = \mathcal{L}(M_2)$



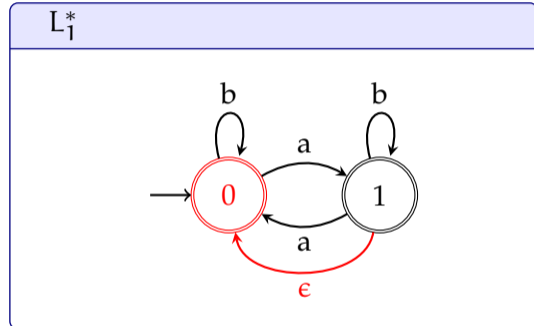
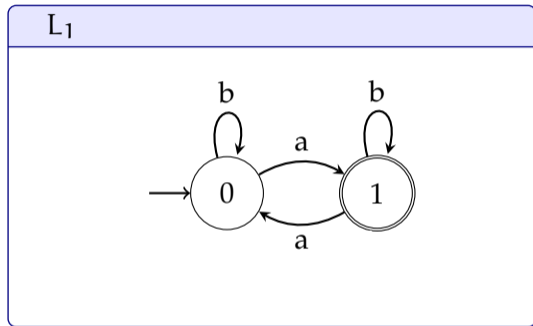
Odd number of  $b$ 's over  $\{a, b\}$ .

We will use these languages and automata for demonstration.

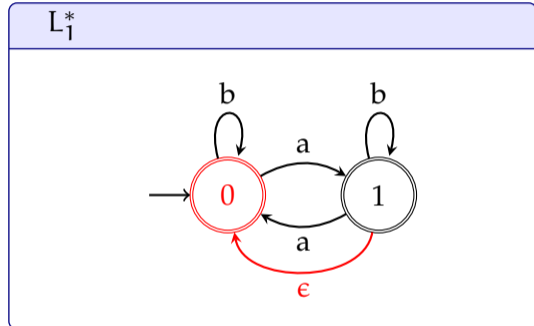
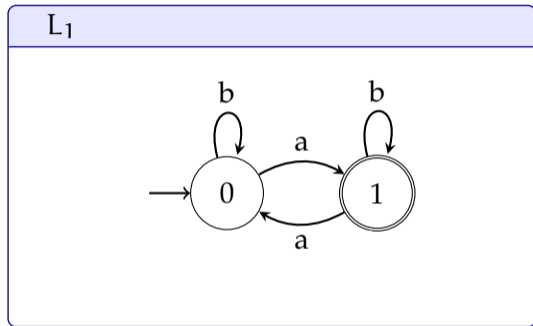
## Concatenation



## Kleene star

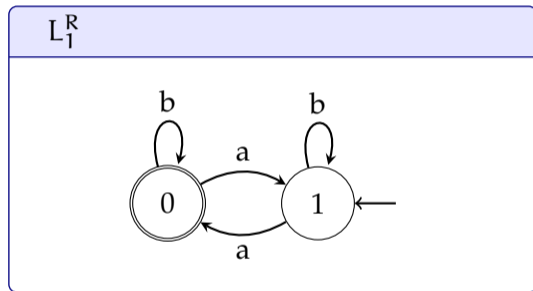
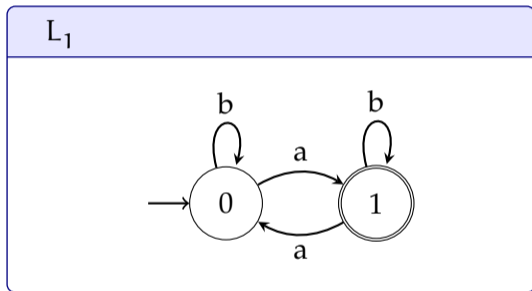


## Kleene star

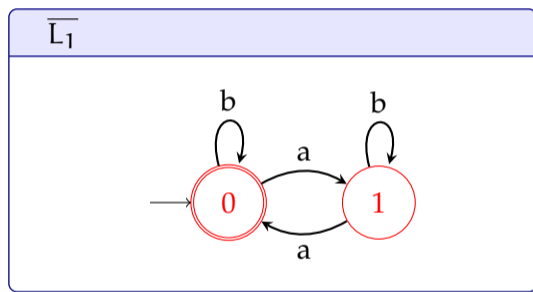
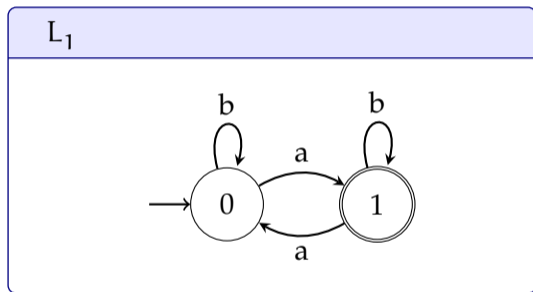


- What if there were more than one accepting states?

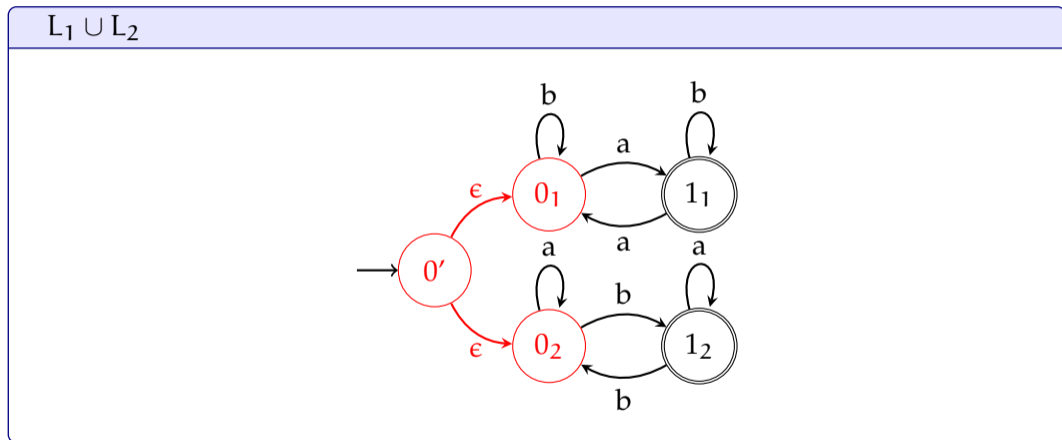
# Reversal



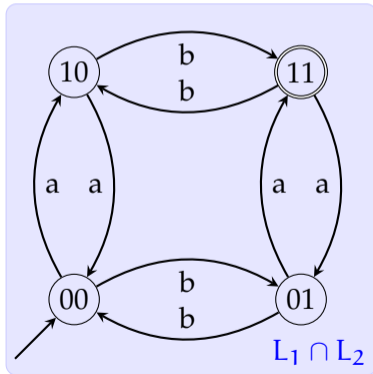
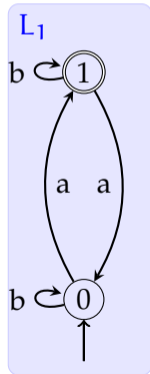
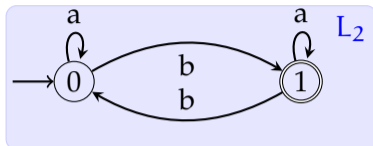
# Complement



## Union

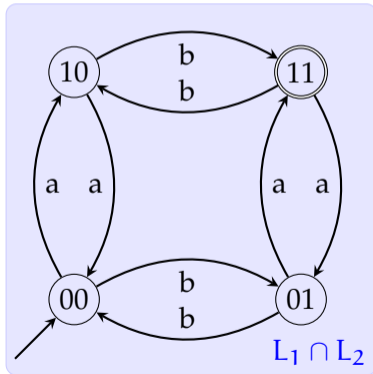
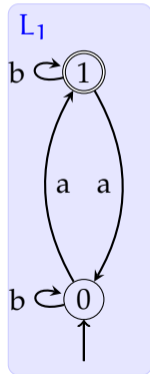
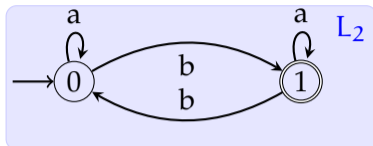


## Intersection





## Intersection



...or

$$L_1 \cap L_2 = \overline{\overline{L_1} \cup \overline{L_2}}$$

# Closure properties of regular languages

- Since results of all the operations we studied are FSA: Regular languages are closed under
  - Concatenation
  - Kleene star
  - Reversal
  - Complement
  - Union
  - Intersection

# Is a language regular?

— or not

- To show that a language is regular, it is sufficient to find an FSA that recognizes it.
- Showing that a language is *not* regular is more involved
- We will study a method based on *pumping lemma*

# Pumping lemma

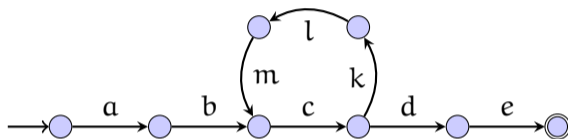
intuition



- What is the length of longest string generated by this FSA?

# Pumping lemma

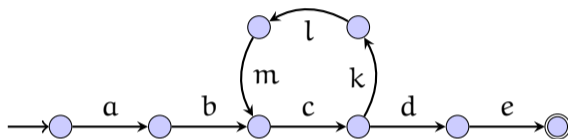
intuition



- What is the length of longest string generated by this FSA?

# Pumping lemma

## intuition



- What is the length of longest string generated by this FSA?
- Any FSA generating an infinite language has to have a loop (application of recursive rule(s) in the grammar)
- Part of every string longer than some number will include repetition of the same substring ('cklm' above)

# Pumping lemma

## definition

For every regular language  $L$ , there exist an integer  $p$  such that a string  $x \in L$  can be factored as  $x = uvw$ ,

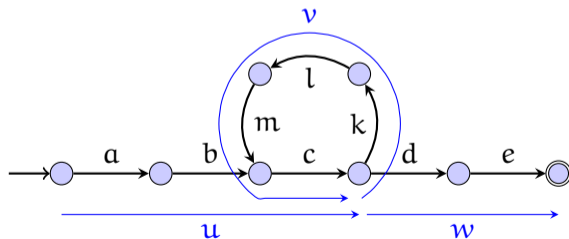
- $uv^i w \in L, \forall i \geq 0$
- $v \neq \epsilon$
- $|uv| \leq p$

# Pumping lemma

## definition

For every regular language  $L$ , there exist an integer  $p$  such that a string  $x \in L$  can be factored as  $x = uvw$ ,

- $uv^i w \in L, \forall i \geq 0$
- $v \neq \epsilon$
- $|uv| \leq p$





# How to use pumping lemma

- We use pumping lemma to prove that a language is not regular
- Proof is by contradiction:
  - Assume the language is regular
  - Find a string  $x$  in the language, for all splits of  $x = uvw$ , at least one of the pumping lemma conditions does not hold
    - $uv^i w \in L$  ( $\forall i \geq 0$ )
    - $v \neq \epsilon$
    - $|uv| \leq p$

# Pumping lemma example

prove  $L = a^n b^n$  is not regular

- Assume  $L$  is regular: there must be a  $p$  such that, if  $uvw$  is in the language
  1.  $uv^i w \in L$  ( $\forall i \geq 0$ )
  2.  $v \neq \epsilon$
  3.  $|uv| \leq p$
- Pick the string  $a^p b^p$
- For the sake of example, assume  $p = 5$ ,  $x = aaaaaabbbbb$
- Three different ways to split

---

$\underbrace{a}_u \underbrace{aaa}_v \underbrace{abbbb}_w$	violates 1
$\underbrace{aaaa}_u \underbrace{ab}_v \underbrace{bbbb}_w$	violates 1 & 3
$\underbrace{aaaaabbbb}_u \underbrace{bbb}_v \underbrace{b}_w$	violates 1 & 3

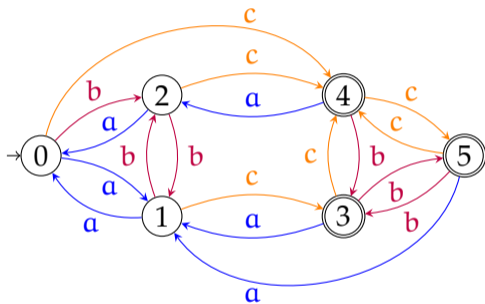
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# DFA minimization

- For any regular language, there is a unique *minimal* DFA
- By finding the minimal DFA, we can also prove equivalence (or not) of different FSA
- In general the idea is:
  - Throw away unreachable states (easy)
  - Merge equivalent states
- There are two well-known algorithms for minimization:
  - Hopcroft's algorithm: find and eliminate equivalent states by partitioning the set of states
  - Brzozowski's algorithm: 'double reversal'

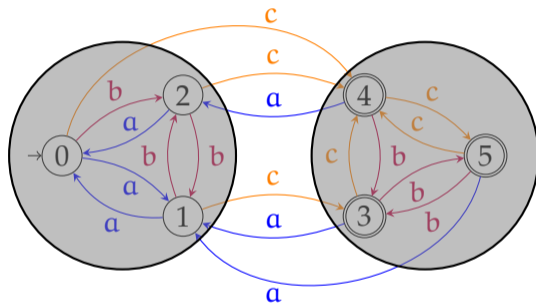
# Finding equivalent states

## Intuition



# Finding equivalent states

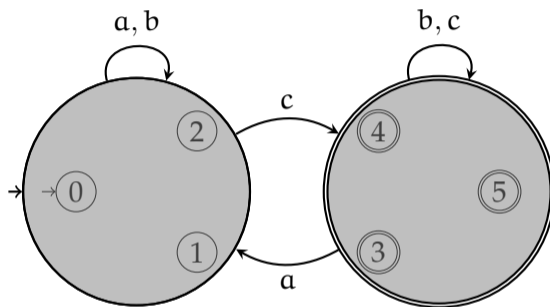
## Intuition



The edges leaving the group of nodes are identical.  
 Their *right languages* are the same.

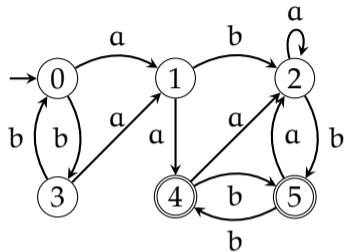
# Finding equivalent states

## Intuition

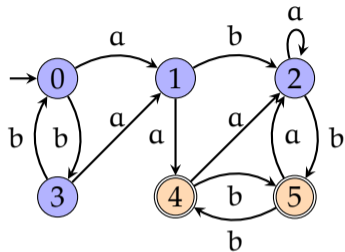


The edges leaving the group of nodes are identical.  
 Their *right languages* are the same.

# Minimization by partitioning



# Minimization by partitioning

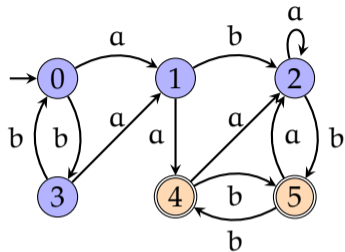


- Accepting & non-accepting states form a partition

$$Q_1 = \{0, 1, 2, 3\}, Q_2 = \{4, 5\}$$

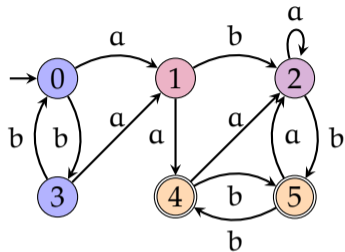


# Minimization by partitioning



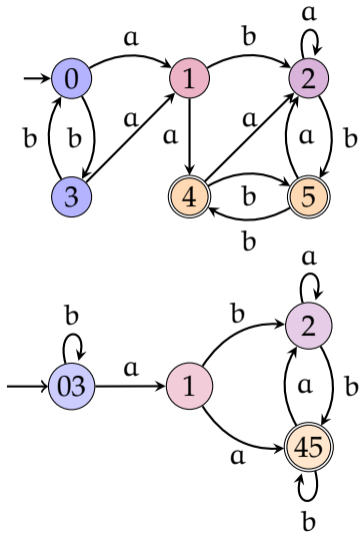
- Accepting & non-accepting states form a partition  
 $Q_1 = \{0, 1, 2, 3\}$ ,  $Q_2 = \{4, 5\}$
- If any two nodes go to different sets for any of the symbols split

# Minimization by partitioning



- Accepting & non-accepting states form a partition  
 $Q_1 = \{0, 1, 2, 3\}, Q_2 = \{4, 5\}$
- If any two nodes go to different sets for any of the symbols split
- $Q_1 = \{0, 3\}, Q_3 = \{1\}, Q_4 = \{2\}, Q_2 = \{4, 5\}$

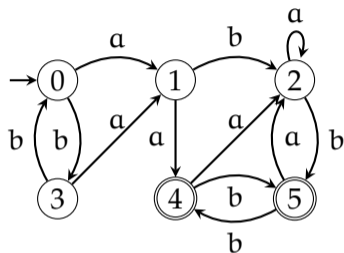
# Minimization by partitioning



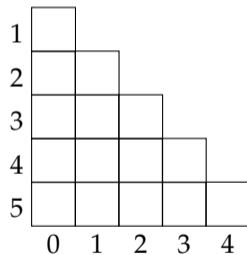
- Accepting & non-accepting states form a partition  
 $Q_1 = \{0, 1, 2, 3\}, Q_2 = \{4, 5\}$
- If any two nodes go to different sets for any of the symbols split
- $Q_1 = \{0, 3\}, Q_3 = \{1\}, Q_4 = \{2\}, Q_2 = \{4, 5\}$
- Stop when we cannot split any of the sets, merge the indistinguishable states

# Minimization by partitioning

tabular version

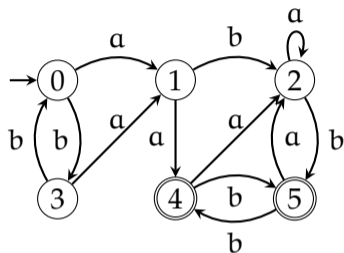


- Create a state-by-state table, mark *distinguishable* pairs:  $(q_1, q_2)$  such that  $(\Delta(q_1, x), \Delta(q_2, x))$  is a distinguishable pair for any  $x \in \Sigma$



# Minimization by partitioning

tabular version

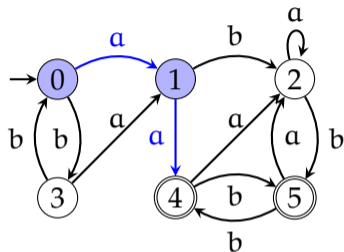


- Create a state-by-state table, mark *distinguishable* pairs:  $(q_1, q_2)$  such that  $(\Delta(q_1, x), \Delta(q_2, x))$  is a distinguishable pair for any  $x \in \Sigma$

1					
2					
3					
4	●	●	●	●	
5	●	●	●	●	
	0	1	2	3	4

# Minimization by partitioning

tabular version

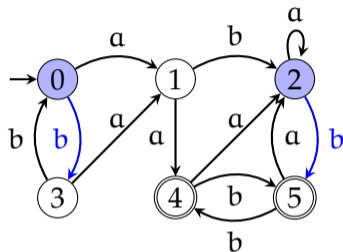


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1					
2					
3					
4	●	●	●	●	
5	●	●	●	●	
	0	1	2	3	4

# Minimization by partitioning

tabular version

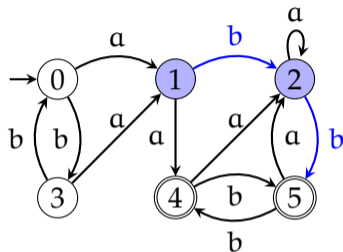


- Create a state-by-state table, mark *distinguishable* pairs:  $(q_1, q_2)$  such that  $(\Delta(q_1, x), \Delta(q_2, x))$  is a distinguishable pair for any  $x \in \Sigma$

1	●				
2					
3					
4	●	●	●	●	
5	●	●	●	●	
	0	1	2	3	4

# Minimization by partitioning

tabular version



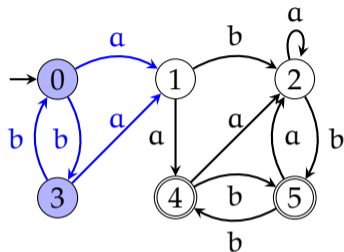
- Create a state-by-state table, mark *distinguishable* pairs:  $(q_1, q_2)$  such that  $(\Delta(q_1, x), \Delta(q_2, x))$  is a distinguishable pair for any  $x \in \Sigma$

1	●				
2	●				
3					
4	●	●	●	●	
5	●	●	●	●	
	0	1	2	3	4



# Minimization by partitioning

tabular version

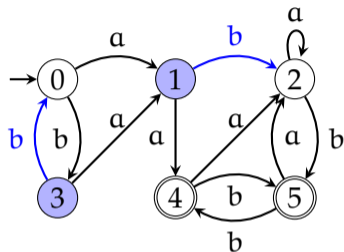


- Create a state-by-state table, mark *distinguishable* pairs:  $(q_1, q_2)$  such that  $(\Delta(q_1, x), \Delta(q_2, x))$  is a distinguishable pair for any  $x \in \Sigma$

1	●	■			
2	●	●			
3	■				
4	●	●	●	●	
5	●	●	●	●	
	0	1	2	3	4

# Minimization by partitioning

tabular version

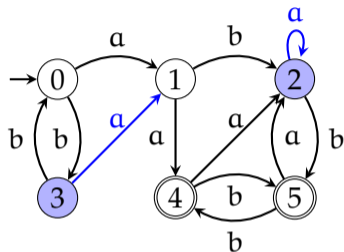


- Create a state-by-state table, mark *distinguishable* pairs:  $(q_1, q_2)$  such that  $(\Delta(q_1, x), \Delta(q_2, x))$  is a distinguishable pair for any  $x \in \Sigma$

1	●				
2	●	●			
3					
4	●	●	●	●	
5	●	●	●	●	
	0	1	2	3	4

# Minimization by partitioning

tabular version

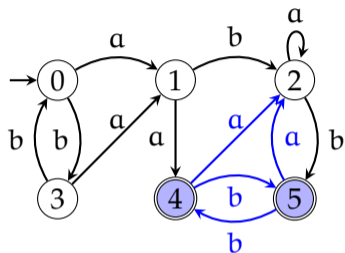


- Create a state-by-state table, mark *distinguishable* pairs:  $(q_1, q_2)$  such that  $(\Delta(q_1, x), \Delta(q_2, x))$  is a distinguishable pair for any  $x \in \Sigma$

1	●				
2	●	●			
3		●			
4	●	●	●	●	
5	●	●	●	●	
	0	1	2	3	4

# Minimization by partitioning

tabular version

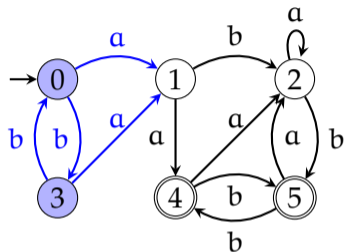


- Create a state-by-state table, mark *distinguishable* pairs:  $(q_1, q_2)$  such that  $(\Delta(q_1, x), \Delta(q_2, x))$  is a distinguishable pair for any  $x \in \Sigma$

1	●				
2	●	●	■		
3		●	●		
4	●	●	●	●	
5	●	●	●	●	■
	0	1	2	3	4

# Minimization by partitioning

tabular version

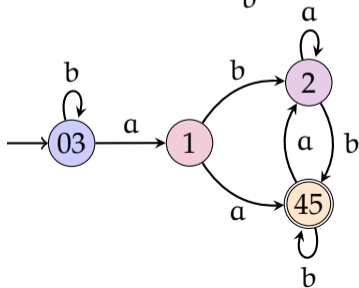
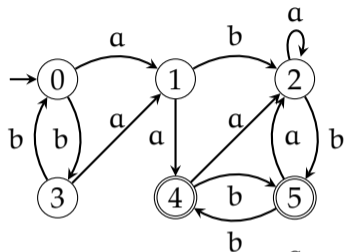


- Create a state-by-state table, mark *distinguishable* pairs:  $(q_1, q_2)$  such that  $(\Delta(q_1, x), \Delta(q_2, x))$  is a distinguishable pair for any  $x \in \Sigma$

1	●	■			
2	●	●			
3	■	●	●		
4	●	●	●	●	
5	●	●	●	●	□
	0	1	2	3	4

# Minimization by partitioning

tabular version



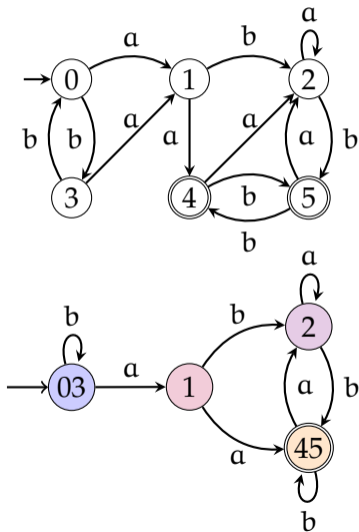
- Create a state-by-state table, mark *distinguishable* pairs:  $(q_1, q_2)$  such that  $(\Delta(q_1, x), \Delta(q_2, x))$  is a distinguishable pair for any  $x \in \Sigma$

1	●				
2	●	●			
3		●	●		
4	●	●	●	●	
5	●	●	●	●	
	0	1	2	3	4

- Merge indistinguishable states

# Minimization by partitioning

tabular version



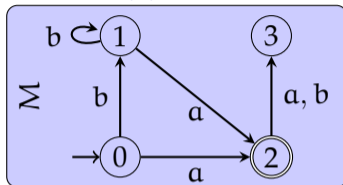
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1	●				
2	●	●			
3		●	●		
4	●	●	●	●	
5	●	●	●	●	
	0	1	2	3	4

- Merge indistinguishable states
- The algorithm can be improved by choosing which cell to visit carefully

# Brzowski's algorithm

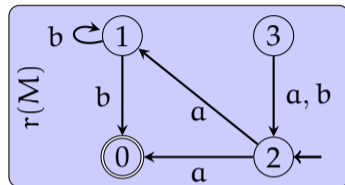
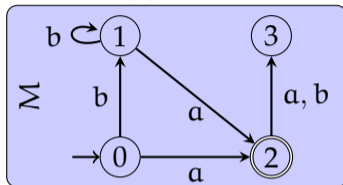
double reverse (r), determinize (d)





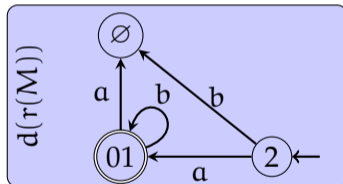
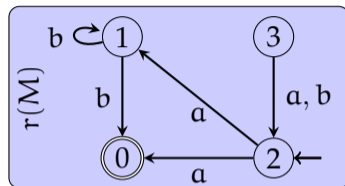
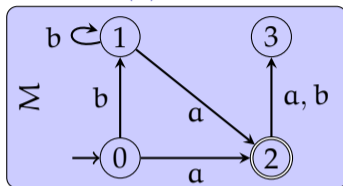
# Brzowski's algorithm

double reverse ( $r$ ), determinize ( $d$ )



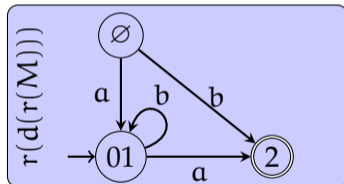
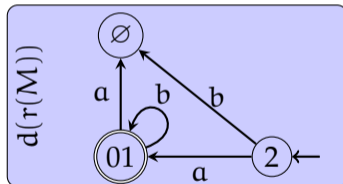
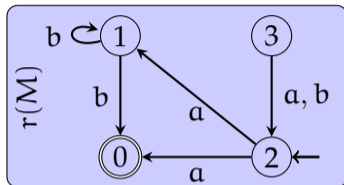
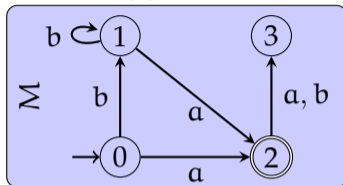
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double reverse ( $r$ ), determinize ( $d$ )



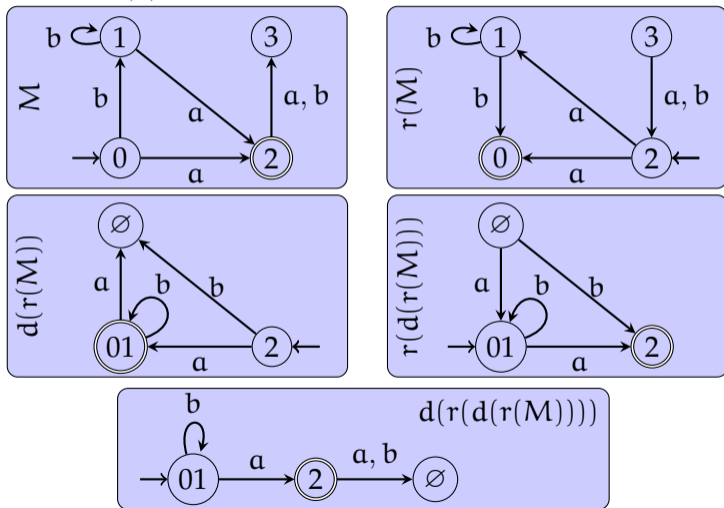
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double reverse ( $r$ ), determinize ( $d$ )



# Brzowski's algorithm

double reverse ( $r$ ), determinize ( $d$ )



# Minimization algorithms

## final remarks

- There are many versions of the ‘partitioning’ algorithm. General idea is to form equivalence classes based on *right-language* of each state.
- Partitioning algorithm has  $O(n \log n)$  complexity
- ‘Double reversal’ algorithm has exponential worst-time complexity
- Double reversal algorithm can also be used with NFAs (resulting in the minimal equivalent DFA – NFA minimization is intractable)
- In practice, there is no clear winner, different algorithms run faster on different input

# Regular expressions

- Another way to specify a regular language (RL) is use of *regular expressions* (RE)
- Every RL can be expressed by a RE, and every RE defines a RL
- A RE  $x$  defines a RL  $\mathcal{L}(x)$
- Relations between RE and RL
  - $\mathcal{L}(\emptyset) = \emptyset,$
  - $\mathcal{L}(\epsilon) = \epsilon,$
  - $\mathcal{L}(a) = a$
  - $\mathcal{L}(ab) = \mathcal{L}(a)\mathcal{L}(b)$
  - $\mathcal{L}(a^*) = \mathcal{L}(a)^*$
  - $\mathcal{L}(a|b) = \mathcal{L}(a) \cup \mathcal{L}(b)$   
(some author use the notation  $a+b$ , we will use  $a|b$  as in many practical implementations)

where,  $a, b \in \Sigma$ ,  $\epsilon$  is empty string,  $\emptyset$  is the language that accepts nothing (e.g.,  $\Sigma^* - \Sigma^*$ )

- Note: no standard complement operation in RE

# Regular

## some extensions

- Kleene star ( $a^*$ ), Concatenation ( $ab$ ) and union ( $a|b$ ) are the common operations
- Parentheses can be used to group the sub-expressions. Otherwise, the priority of the operators as specified above  $a|bc^* = a|(b(c^*))$
- In practice some short-hand notations are common
  - $\Sigma = (a_1 | \dots | a_n)$ ,  
for  $\Sigma = \{a_1, \dots, a_n\}$
  - $a^+ = aa^*$
  - $[a-c] = (a|b|c)$
  - $[\hat{a-c}] = \Sigma - (a|b|c)$
  - $\backslash d = (0|1|\dots|8|9)$
  - ...
- And some non-regular extensions, like  $(a^*)b\backslash 1$  (sometimes the term *regex* is used for expressions with non-regular extensions)

# Some properties of regular expressions

## Kleene algebra

These identities are often used to simplify regular expressions.

- $\epsilon u = u$
- $\emptyset u = \emptyset$
- $u(vw) = (uv)w$
- $\emptyset^* = \epsilon$
- $\epsilon^* = \epsilon$
- $(u^*)^* = u^*$
- $u|v = v|u$
- $u|u = u$
- $u|\emptyset = u$
- $u|\epsilon = u$
- $u|(v|w) = (u|v)|w$
- $u(v|w) = uv|uw$
- $(u|v)^* = (u^*|v^*)^*$

Note: most of these follow from set theory, and some can be derived from others.



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### An exercise

Simplify  $a|ab^*$

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### An exercise

Simplify  $a|ab^*$

$$a|ab^* = a\epsilon|ab^*$$

Note: most of these follow from set theory, and some can be derived from others.

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### An exercise

Simplify  $a|ab^*$

$$\begin{aligned} a|ab^* &= a\epsilon|ab^* \\ &= a(\epsilon|b^*) \end{aligned}$$

Note: most of these follow from set theory, and some can be derived from others.

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### An exercise

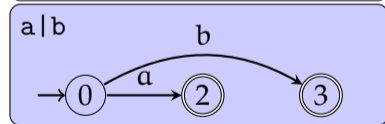
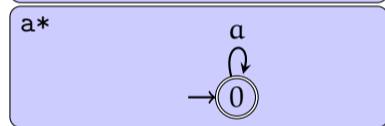
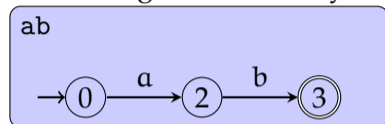
Simplify  $a|ab^*$

$$\begin{aligned} a|ab^* &= a\epsilon|ab^* \\ &= a(\epsilon|b^*) \\ &= ab^* \end{aligned}$$

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# Converting regular expressions to FSA

Converting to NFA is easy:

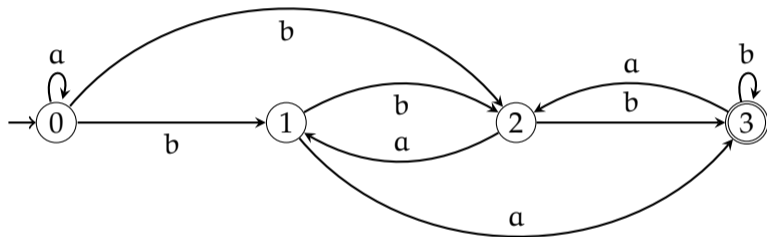


Note the similarity with operations on regular languages discussed earlier.

- For more complex expressions, one can replace the paths for individual symbols with corresponding automata
- Using  $\epsilon$  transitions may be ease the task
- The reverse conversion (from automata to regular expressions) is also easy:
  - identify the patterns on the left, collapse paths to single transitions with regular expressions

# Converting FSA to regular expressions

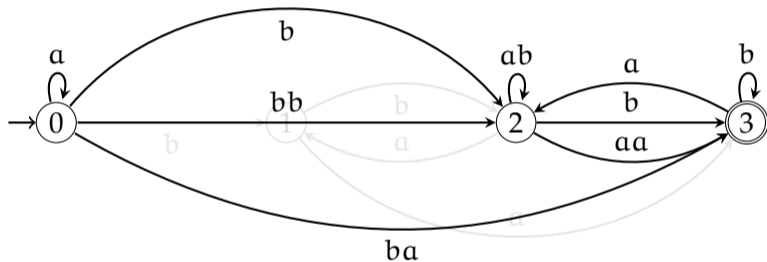
Converting an FSA to a regular expression is also easy:



- The general idea: remove (intermediate) states, replacing edge labels with regular expressions

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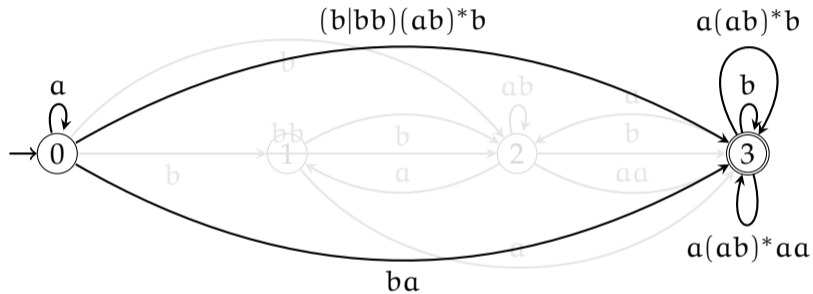
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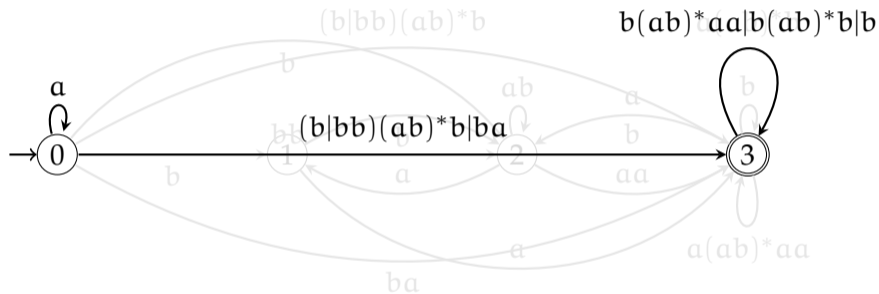


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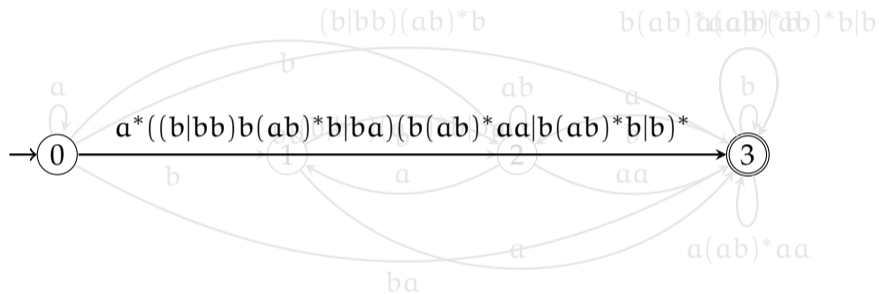
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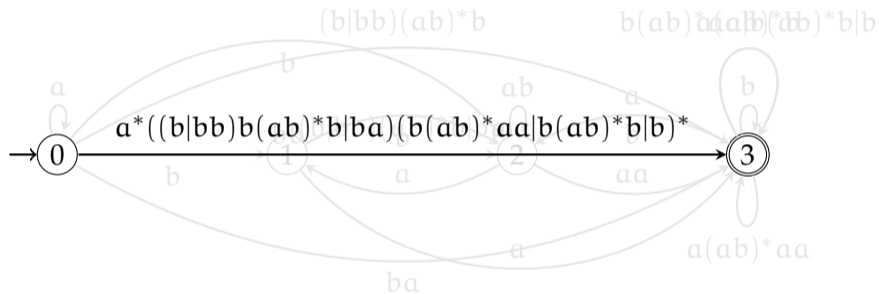
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An exercise: simplify the resulting regular expressions

## Wrapping up

- FSA and regular expressions express regular languages
- FSA have two flavors: DFA, NFA (or maybe three:  $\epsilon$ -NFA)
- DFA recognition is linear
- Any NFA can be converted to a DFA (in worst case number of nodes increase exponentially)
- Regular languages and FSA are closed under
  - Concatenation
  - Kleene star
  - Complement
  - Reversal
  - Union
  - Intersection
- Every FSA has a unique minimal DFA

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Next:

- Finite state transducers (FSTs)
- Applications of FSA and FSTs

## References / additional reading material

- Hopcroft and Ullman (1979, Ch. 2&3) (and its successive editions) covers (almost) all topics discussed here
- Jurafsky and Martin (2009, Ch. 2)
- Other textbook references include:
  - Sipser (2006)
  - Kozen (2013)

## References / additional reading material (cont.)

Hopcroft, John E. and Jeffrey D. Ullman (1979). *Introduction to Automata Theory, Languages, and Computation*. Addison-Wesley Series in Computer Science and Information Processing. Addison-Wesley. ISBN: 9780201029888.

Jurafsky, Daniel and James H. Martin (2009). *Speech and Language Processing: An Introduction to Natural Language Processing, Computational Linguistics, and Speech Recognition*. second. Pearson Prentice Hall. ISBN: 978-0-13-504196-3.

Kozen, Dexter C. (2013). *Automata and Computability*. Undergraduate Texts in Computer Science. Berlin Heidelberg: Springer.

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